

6-4 Take q at $(0, 0, z_0)$ & $\vec{p} = p_0(\hat{u} \sin \phi + \hat{k} \cos \phi)$
at $(0, 0, z_0)$.

$$a) U(\vec{x}) = -\vec{p} \cdot \vec{E}(\vec{x})$$

$$\vec{F}_{\text{dipole}} = -\vec{\nabla} U = \vec{\nabla}(\vec{p} \cdot \vec{E}(\vec{x}))$$

Alternatively,

$$\vec{E} = -\vec{\nabla} V$$

$$\vec{\nabla}(\vec{p} \cdot \vec{E}) = -\hat{e}_i \frac{\partial}{\partial x_i} p_j \frac{\partial V}{\partial x_j} = -\hat{e}_i p_j \frac{\partial^2 V}{\partial x_i \partial x_j}$$

$$= (p_j \frac{\partial}{\partial x_j})(-\hat{e}_i \frac{\partial V}{\partial x_i}) = (\vec{p} \cdot \vec{\nabla}) \vec{E}$$

$$b) \vec{E} = q\vec{x} / 4\pi\epsilon_0 r^3$$

$$\vec{p} \cdot \vec{E} = \frac{p_0 q}{4\pi\epsilon_0 r^3} [x \sin \phi + z \cos \phi]$$

$$\vec{F} = \vec{\nabla}(\vec{p} \cdot \vec{E}) = \frac{p_0 q}{4\pi\epsilon_0} \left[\frac{-3\hat{r}}{r^4} (x \sin \phi + z \cos \phi) + \frac{1}{r^3} (\hat{u} \sin \phi + \hat{k} \cos \phi) \right]$$

but if \vec{p} has position $(0, 0, z_0)$, $\hat{r} = \hat{k}$, $r = z_0$

$$\vec{F} = \frac{p_0 q}{4\pi\epsilon_0 z_0^3} [-2\hat{k} \cos \phi + \hat{u} \sin \phi]$$

$$\vec{\tau} = \vec{p} \times \vec{E} = p_0 [\hat{u} \sin \phi + \hat{k} \cos \phi] \times \frac{q\vec{x}}{4\pi\epsilon_0 r^3}$$

$$= -\frac{p_0 q}{4\pi\epsilon_0 z_0^3} \sin \phi \hat{j}$$

$$\vec{E}_{\text{dip}} = \frac{1}{4\pi\epsilon_0 r^3} [3\hat{r}(\hat{r} \cdot \vec{p}) - \vec{p}]$$

$$\vec{F} = q\vec{E} = \frac{z p_0}{4\pi\epsilon_0 z^3} [2\hat{k} \cos \phi - \hat{u} \sin \phi]$$